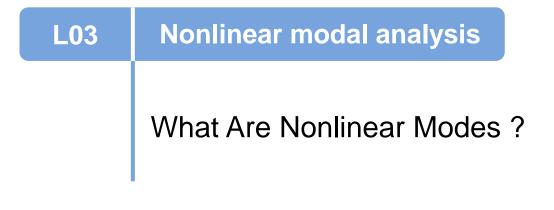
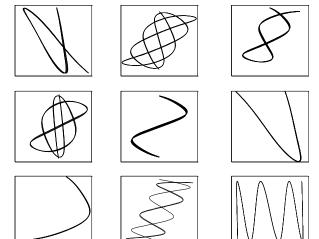
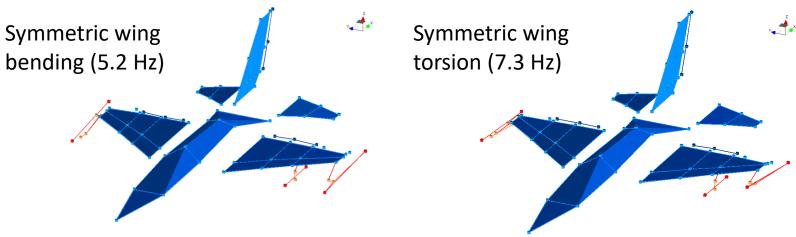
## Nonlinear Vibrations of Aerospace Structures





#### Modal Analysis Provides Key Information





#### 2.2. Modes normaux de vibration

Pour résoudre les équations des petites oscillations libres (2.1.12)

$$M\ddot{q} + Kq = 0$$

cherchons une solution particulière dans laquelle toutes les coordonnées généralisées suivent, à un facteur près, la même loi temporelle

$$\mathbf{q} = \mathbf{x} \ \phi(t) \tag{2.2.1}$$

où x est un vecteur de constantes constituant la forme propre du mouvement, propre dans ce sens que le rapport de deux coordonnées est indépendant du temps et est toujours égal au rapport des éléments correspondants de x. L'essai d'une solution de ce type fournit

$$\ddot{\phi}(t)\mathbf{M}\mathbf{x} + \phi(t)\mathbf{K}\mathbf{x} = \mathbf{0}$$
(2.2.2)

Cours de théorie des vibrations

### How Do We Calculate Linear Normal Modes ?

$$\ddot{q}_1 + (2q_1 - q_2) = 0$$
  
$$\ddot{q}_2 + (2q_2 - q_1) = 0$$

#### How Do We Calculate Linear Normal Modes ?

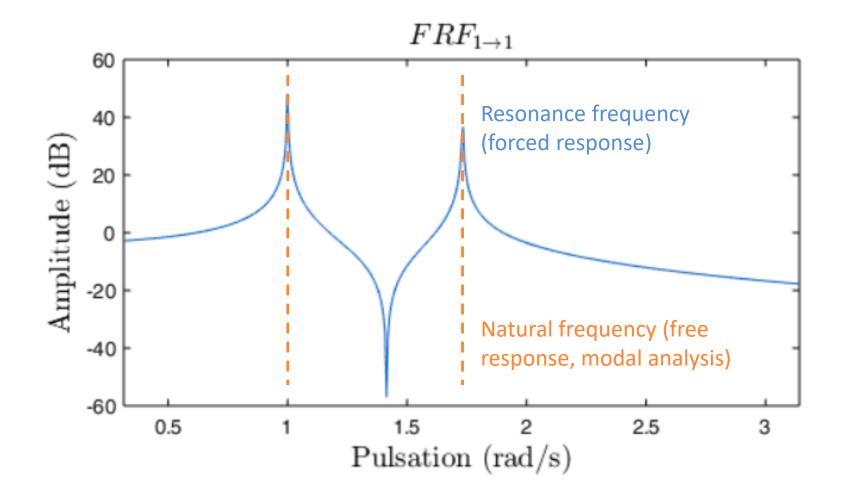
$$\begin{array}{c} q_{1,2} = A, Bcos\omega t \\ \hline q_1 + (2q_1 - q_2) = 0 \\ \hline q_2 + (2q_2 - q_1) = 0 \end{array} \qquad -\omega^2 A + 2A - B = 0 \\ -\omega^2 B + 2B - A = 0 \end{array}$$

$$\begin{array}{c} -\omega^2 A(2 - \omega^2) \\ + 2A(2 - \omega^2) - A = 0 \end{array} \qquad B = A(2 - \omega^2) \\ -\omega^2 B + 2B - A = 0 \end{array}$$

$$\begin{array}{c} \omega_1 = 1 \text{ rad/s with } A = B, \\ \omega_2 = \sqrt{3} \text{ rad/s with } A = -B, \end{array}$$

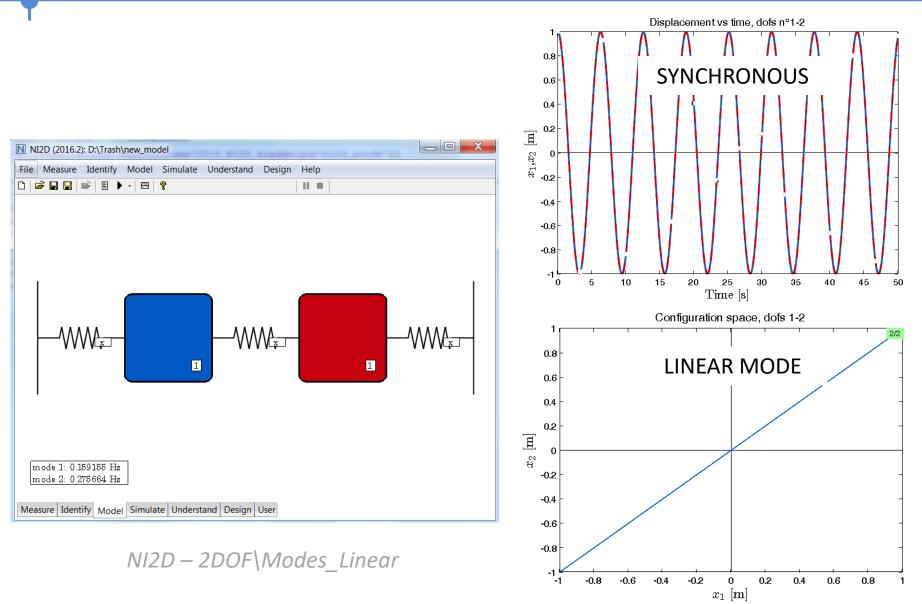
Linear modes are invariant

#### Link Between Natural and Resonance Frequencies

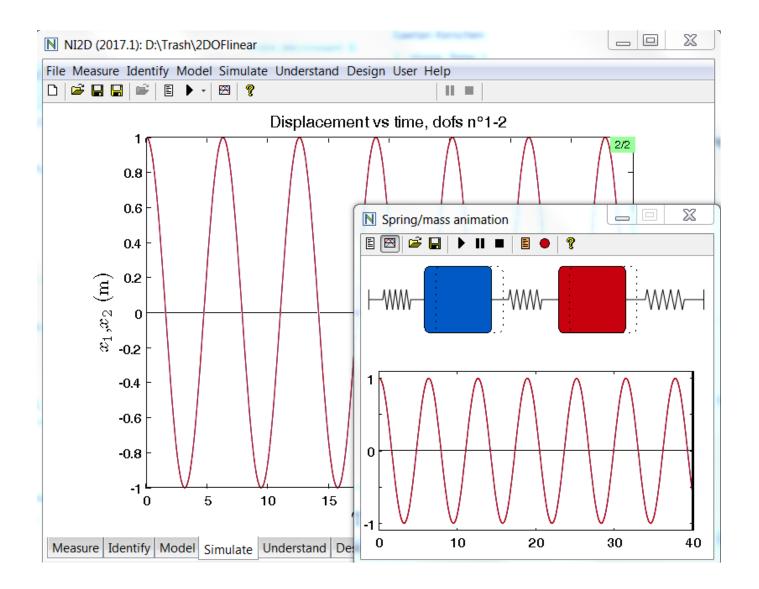


NI2D – 2DOF\Modes\_Linear

#### Properties of Linear Modes ?



#### Properties of Linear Modes ?



#### Phase Quadrature

#### a. Critère de la quadrature de phase

Lorsque l'on réalise un essai de vibration harmonique sur un système amorti, les amplitudes des forces appliquées et les amplitudes des réponses observées aux différents points vérifient la relation complexe (3.1.18)

$$\left(\mathbf{K} - \omega^2 \mathbf{M} + i\omega \mathbf{C}\right)\mathbf{z} = \mathbf{f}$$
(3.1.21)

Isoler un mode propre par une excitation appropriée revient à réaliser

$$\mathbf{z} = \mathbf{x}_{(k)}$$
 et  $\omega = \omega_{0k}$ 

L'équation (3.1.21) devient alors

$$\left(\mathbf{K} - \omega_{0k}^{2}\mathbf{M} + i\omega_{0k}\mathbf{C}\right)\mathbf{x}_{(k)} = \mathbf{f}_{(k)}$$
(3.1.22)

Cours de théorie des vibrations

où  $f_{(k)}$  est le mode de sollicitation qui permet de réaliser l'excitation appropriée.  $\omega_{0k}^2$  et  $\mathbf{x}_{(k)}$  étant solutions propres du système conservatif associé, on a

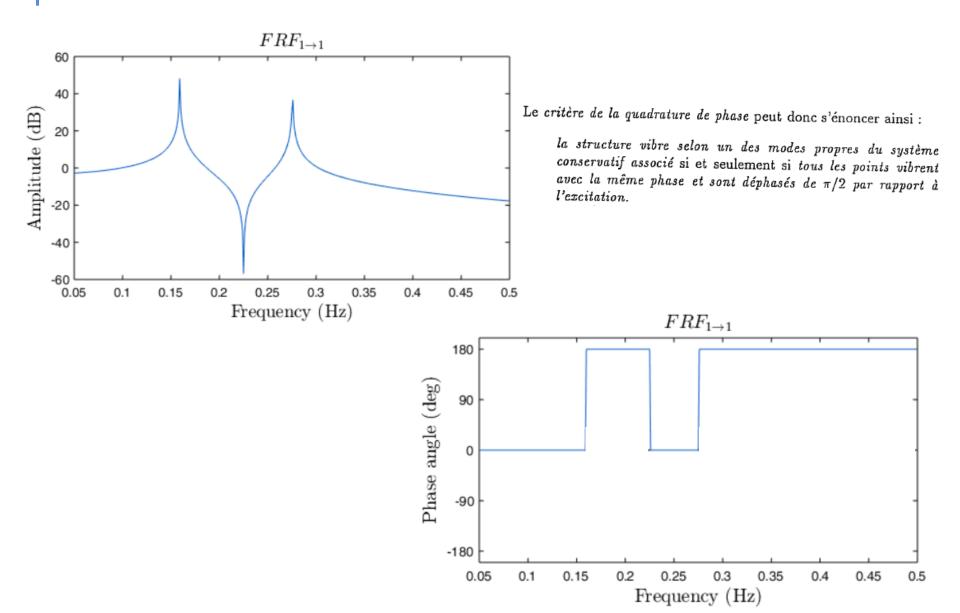
$$\left(\mathbf{K}-\omega_{0k}^{2}\mathbf{M}\right)\mathbf{x}_{(k)}=\mathbf{0}$$

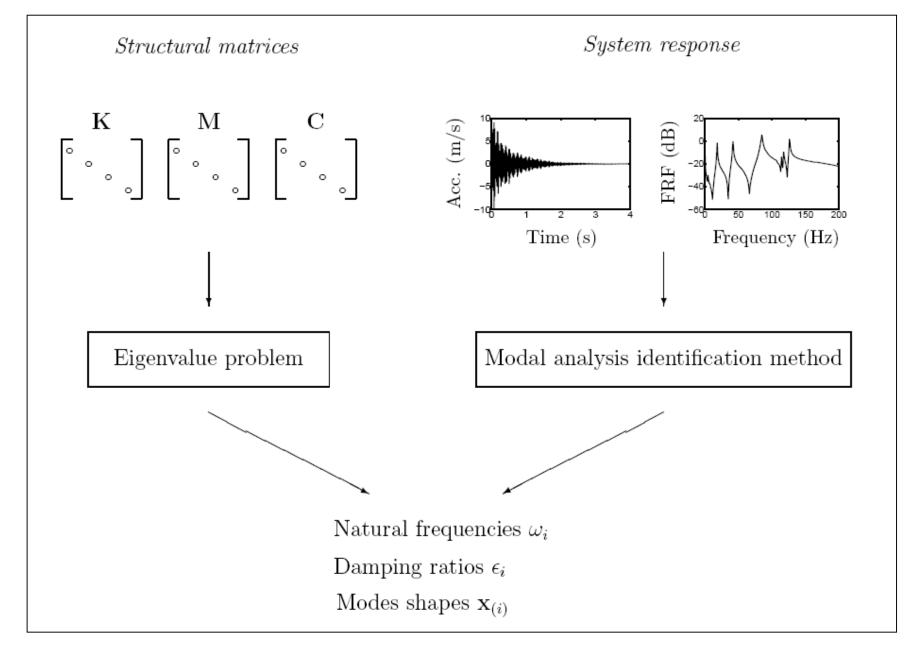
et l'expression de la sollicitation qui permet d'exciter le mode  $\mathbf{x}_{(k)}$  à sa fréquence de résonance découle de l'équation (3.1.22)

$$\mathbf{f}_{(k)} = i\omega_{0k} \mathbf{C} \mathbf{x}_{(k)} \tag{3.1.23}$$

Elle montre que la sollicitation est alors en phase avec les forces de dissipation et présente donc un déphasage de 90° par rapport à la réponse.

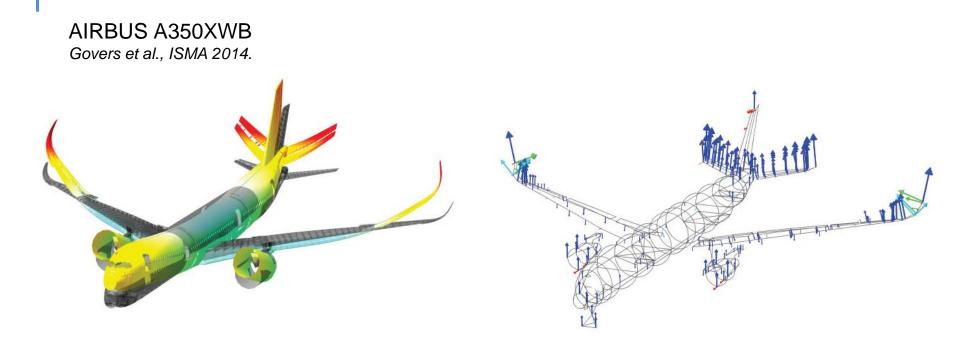
#### Phase Quadrature





Theoretical and experimental modal analysis (TMA and EMA)

#### Industrial Use of the Concept of Modes



Design is based on shaping resonances (eigenvalue solver in all commercial FE packages).

Certification is based on measuring resonances

(stochastic subspace identification, eigensystem realization, PolyMAX, ...). What are nonlinear modes ?

What are their fundamental properties ?

Link between modes and resonance frequencies

A tutorial

For n-DOF conservative systems with no internal resonances, there exist at least n different families of periodic solutions around the stable equilibrium point of the system. For n-DOF conservative systems with no internal resonances, there exist at least n different families of periodic solutions around the stable equilibrium point of the system.

At low energy, the periodic solutions of each family are in the neighborhood of a LNM of the linearized system. These n families define n NNMs that can be regarded as nonlinear extensions of the n LNMs of the underlying linear system.

## Rosenberg (1960s): Nonlinear Normal Modes

An NNM is a synchronous vibration of the system:

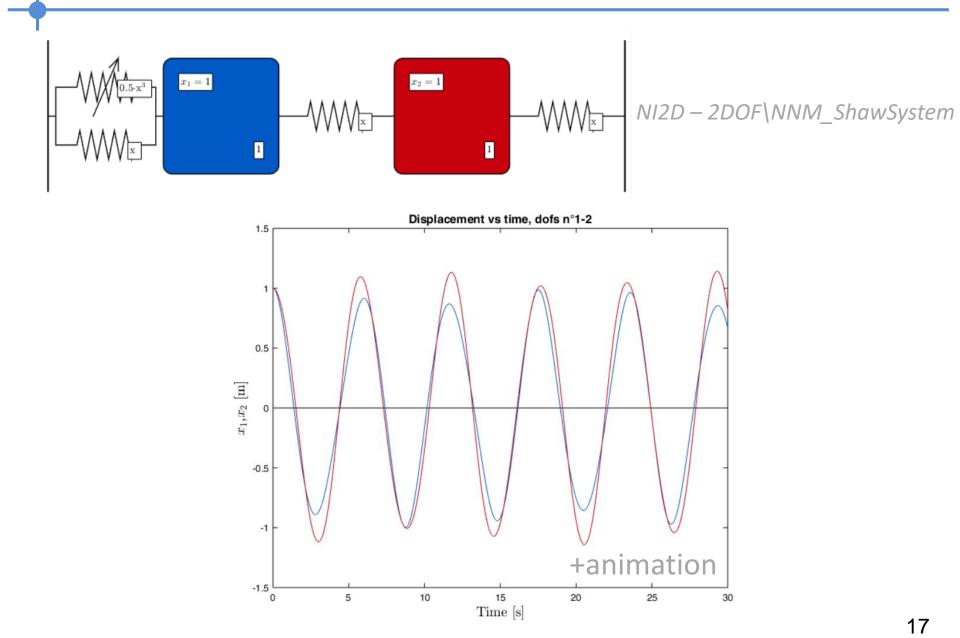
- All material points of the system reach their extreme values and pass through zero simultaneously.
- The system behaves like a nonlinear single-DOF system when it vibrates along an NNM.

$$M\ddot{x}(t) + Kx(t) = 0$$
  $M\ddot{x}(t) + Kx(t) + f_{NL}[x(t)] = 0$ 

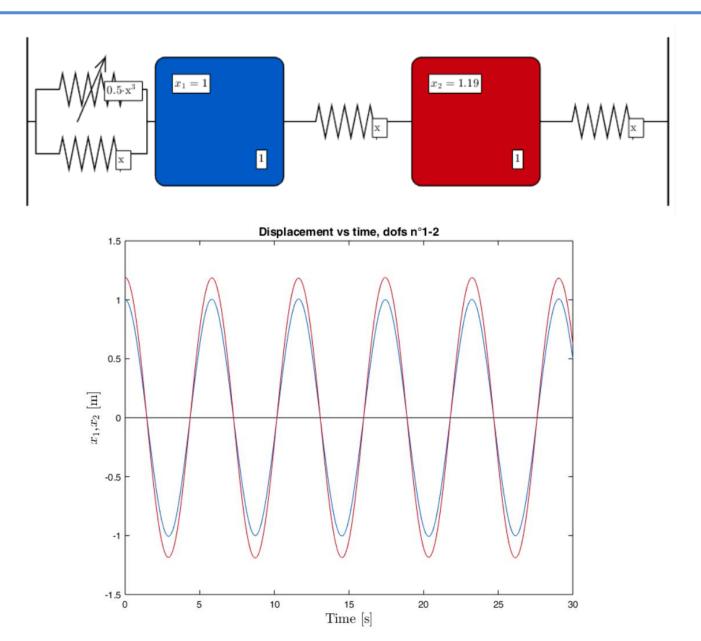
LNM: synchronous periodic motion.

NNM: synchronous periodic motion.

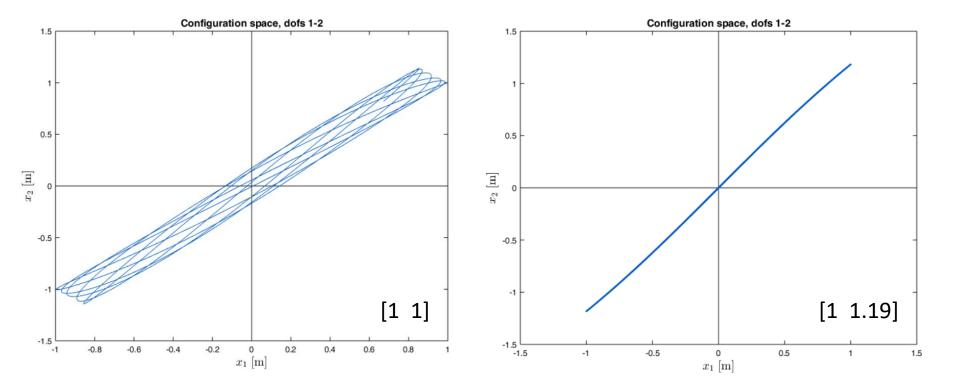
#### Is This a Nonlinear Mode ?



#### Is This a Nonlinear Mode ?

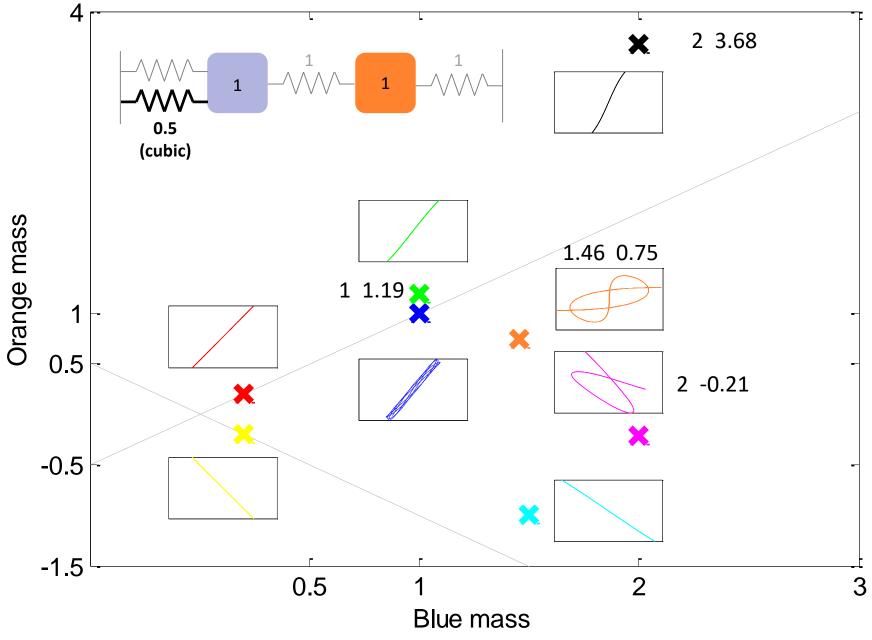


#### Is This a Nonlinear Mode ?



#### NI2D DEMO WITH CONFIGURATION SPACE

Initial conditions on displacements



### How Do We Calculate Nonlinear Normal Modes ?

$$\ddot{q}_1 + (2q_1 - q_2) + 0.5q_1^3 = 0$$
  
$$\ddot{q}_2 + (2q_2 - q_1) = 0$$

## How Do We Calculate Nonlinear Normal Modes ?

$$(x) 30 = 4\omega^{3} 0 - 3\omega 0$$
  

$$= \omega^{3} 0 = \frac{4}{4} (\omega^{3} 0 + 3\omega 0)$$
  

$$\vec{q}_{2} + 2q_{2} - q_{2} + \frac{4}{2} q_{2}^{3} = 0 \qquad -\omega^{2} A + 2A - B + \frac{3}{8} A^{3} = 0 \qquad (4)$$
  

$$\vec{q}_{2} + 2q_{1} - q_{1} = 0 \qquad -\omega^{2} B + 2B - A = 0 \qquad = B = \frac{A}{2 - \omega^{2}} (e)$$
  

$$(A) h(2) \Rightarrow -\omega^{2} A + 2A - \frac{A}{2 - \omega^{2}} + \frac{3}{8} A^{3} = 0$$
  

$$\Rightarrow -\omega^{2} + 2 - \frac{1}{2 - \omega^{2}} + \frac{3}{8} A^{2} = 0$$
  

$$\Rightarrow -2\omega^{2} + \omega^{4} + 4 - 2\omega^{2} - 4 + \frac{3}{8} A^{2} - \frac{3}{8} A^{2} \omega^{2} = 0$$
  

$$\Rightarrow A^{2} \left(\frac{3}{4} - \frac{3}{8} \omega^{2}\right) = -\omega^{4} + 4\omega^{2} - 3$$
  

$$\Rightarrow A^{2} \left(\frac{3}{4} - \frac{3}{8} \omega^{2}\right) = -\omega^{4} + 4\omega^{2} - 3$$
  

$$\Rightarrow A^{2} \left(\frac{3}{4} - \frac{3}{8} \omega^{2}\right) = -\omega^{4} + 4\omega^{2} - 3$$

$$\ddot{q}_{1} + (2q_{1} - q_{2}) = 0$$
  
 $\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$   
 $q_{1,2} = A, Bcos\omega t$   
 $\ddot{q}_{1,2} = A, Bcos\omega t$   
 $\ddot{q}_{1,2} = A, Bcos\omega t$   
 $\ddot{q}_{1,2} \cong A, Bcos\omega t$   
 $A = B, \ \omega_{1} = 1 \ rad/s$   
 $A = -B, \ \omega_{2} = \sqrt{3} \ rad/s$   
 $\ddot{q}_{1} + (2q_{1} - q_{2}) + 0.5q_{1}^{3} = 0$   
 $\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$   
 $q_{1,2} \cong A, Bcos\omega t$   
 $A = \pm \sqrt{\frac{8(\omega^{2} - 3)(\omega^{2} - 1)}{3(\omega^{2} - 2)}}$   
 $B = \frac{A}{2 - \omega^{2}}$ 

# 2 fundamental differences !

Which ones ?

$$\ddot{q}_{1} + (2q_{1} - q_{2}) = 0$$
  
 $\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$   
 $q_{1,2} = A, Bcos\omega t$   
 $\vec{q}_{1} + (2q_{1} - q_{2}) + 0.5q_{1}^{3} = 0$   
 $\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$   
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 $A = -B, \ \omega_{2} = \sqrt{3} \text{ rad/s}$   
 $A = \frac{A}{2 - \omega^{2}}$ 

1. Modal shapes depend on frequency

$$\ddot{q}_{1} + (2q_{1} - q_{2}) = 0$$
  
$$\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$$
  
$$q_{1,2} = A, Bcos\omega t$$
  
$$A = B, \ \omega_{1} = 1 \text{ rad/s}$$
  
$$A = -B, \ \omega_{2} = \sqrt{3} \text{ rad/s}$$

$$\ddot{q}_{1} + (2q_{1} - q_{2}) + 0.5q_{1}^{3} = 0$$
  
$$\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$$
  
$$q_{1,2} \cong A, Bcos\omega t$$

$$A = \pm \sqrt{\frac{8(\omega^2 - 3)(\omega^2 - 1)}{3(\omega^2 - 2)}}$$
$$B = \frac{A}{2 - \omega^2}$$

2. The natural frequency is not fixed (but existence conditions !)

$$\ddot{q}_{1} + (2q_{1} - q_{2}) = 0$$
  
$$\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$$
  
$$q_{1,2} = A, Bcos\omega t$$

$$\ddot{q}_{1} + (2q_{1} - q_{2}) + 0.5q_{1}^{3} = 0$$
  
$$\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$$
  
$$q_{1,2} \cong A, Bcos\omega t$$

$$A = \pm \sqrt{\frac{8(\omega^2 - 3)(\omega^2 - 1)}{3(\omega^2 - 2)}}$$
$$B = \frac{A}{2 - \omega^2}$$

$$\omega_1 \in \left[1, \sqrt{2}\right[ \text{ rad/s}$$
  
 $\omega_2 \in \left[\sqrt{3}, +\infty\right[ \text{ rad/s}\right]$ 

Existence conditions for NNM

$$A = B$$
,  $\omega_1 = 1 \text{ rad/s}$ 

$$A = -B$$
,  $\omega_2 = \sqrt{3}$  rad/s

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#### **Useful Graphical Representation**

$$\ddot{q}_1 + (2q_1 - q_2) + 0.5q_1^3 = 0$$
  
$$\ddot{q}_2 + (2q_2 - q_1) = 0$$

Initial conditions:  $[q_1(0) \ q_2(0) \ \dot{q_1}(0) \ \dot{q_2}(0)] = [A \ B \ 0 \ 0]$ 

Total energy =  
initial potential energy : 
$$E = V = \frac{A^2}{2} + \frac{(B-A)^2}{2} + \frac{B^2}{2} + \frac{0.5A^4}{4}$$

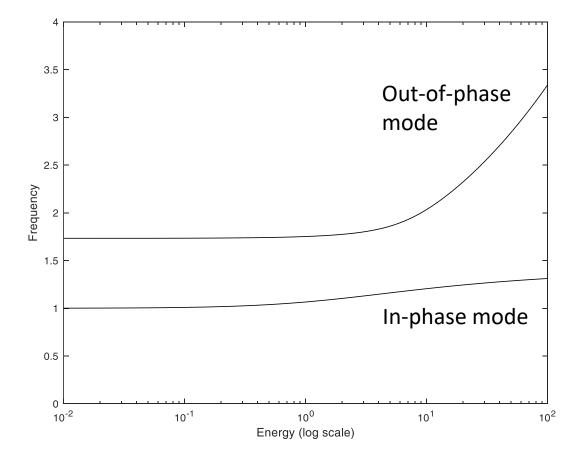
A frequency-energy plot is calculated by

- Selecting a frequency in the interval provided by the existence conditions,
- Calculating A and B according to the analytical formulas
- Calculating the corresponding total energy
- Representing the frequency as a function of the total energy

#### In Matlab

```
HB1_2DOF_FEP.m 🛛 🕂
    clear all
    close all
    cpt=1;
  _ for omeg=1.00001:0.001:sqrt(2)
        A=sqrt(8*(omeg^2-3)*(omeg^2-1)/3/((omeg^2-2)));
-
        B=A/(2-omeg^2);
        NRJ(cpt)=(A-B)^2/2+A^2/2+B^2/2+0.5*A^4/4;
_
-
        freq(cpt)=omeg;
        AIP(cpt)=A;
        BIP(cpt)=B;
         cpt=cpt+1;
     end
_
     semilogx(NRJ,freq,'k')
    cpt=1;
   _ for omeg=sqrt(3)+0.0000001:0.001:4
-
        A=sqrt(8*(omeg^2-3)*(omeg^2-1)/3/((omeg^2-2)));
        B=A/(2-omeg^2);
-
        NRJ2(cpt) = (A-B)^{2/2}+A^{2/2}+B^{2/2}+0.5*A^{4/4};
-
        freq2(cpt)=omeg;
        AOP(cpt)=A;
         BOP(cpt)=B;
         cpt=cpt+1;
    ∟end
     hold on
    semilogx(NRJ2,freq2,'k')
```

#### A Frequency-Energy Plot Is a Convenient Depiction



#### Limitation of Analytical Calculations

$$\ddot{q}_{1} + (2q_{1} - q_{2}) + 0.5q_{1}^{3} = 0$$
  
$$\ddot{q}_{2} + (2q_{2} - q_{1}) = 0$$
  
$$q_{1,2} \cong A, Bcos\omega t$$

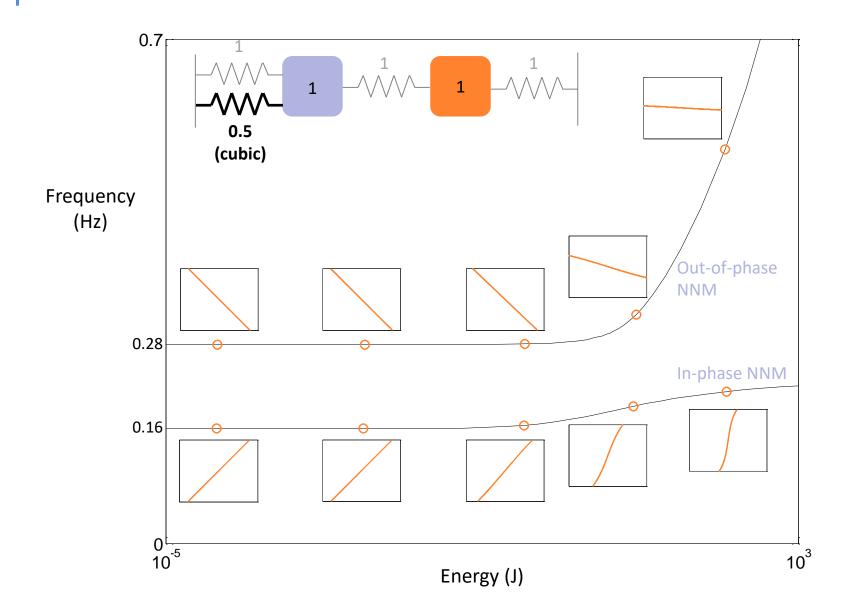
$$A = \pm \sqrt{\frac{8(\omega^2 - 3)(\omega^2 - 1)}{3(\omega^2 - 2)}}$$
$$B = \frac{A}{2 - \omega^2}$$

A 1-term harmonic balance approximation cannot calculate the curvature of nonlinear modes

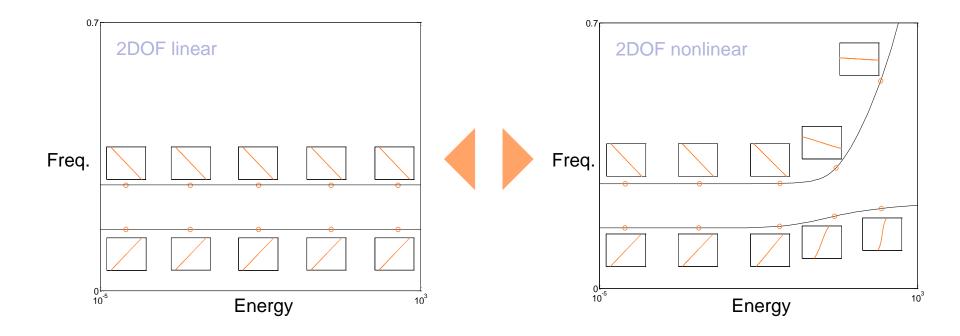
#### **Numerical Calculation**



### « Curved » Nonlinear Modes Are Now Obtained



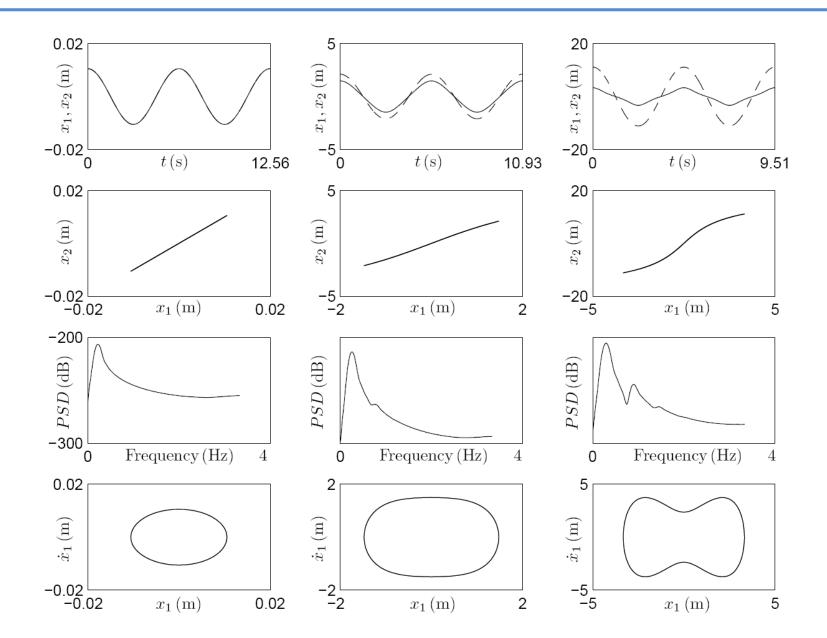
#### Linear Modes vs. Nonlinear Modes



But ... Frequency-energy dependence

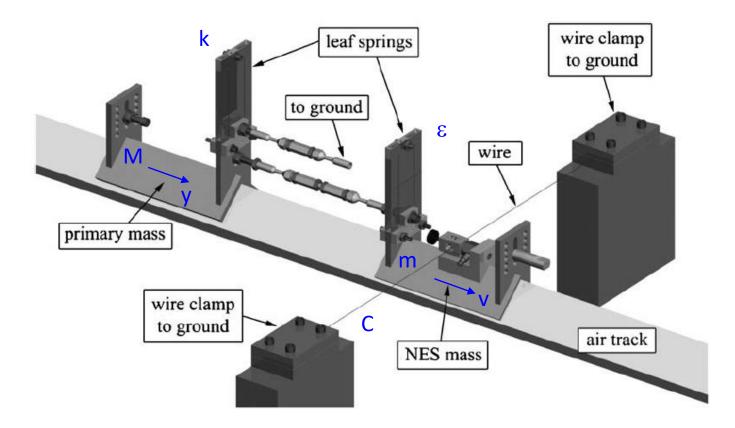
And other important differences

#### The In-Phase NNM for Increasing Energies

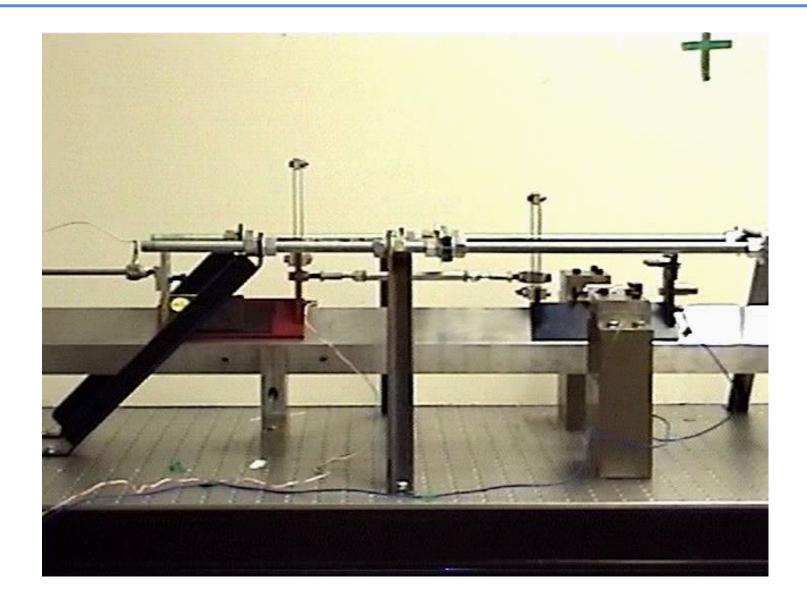


#### **Experimental Demonstration**

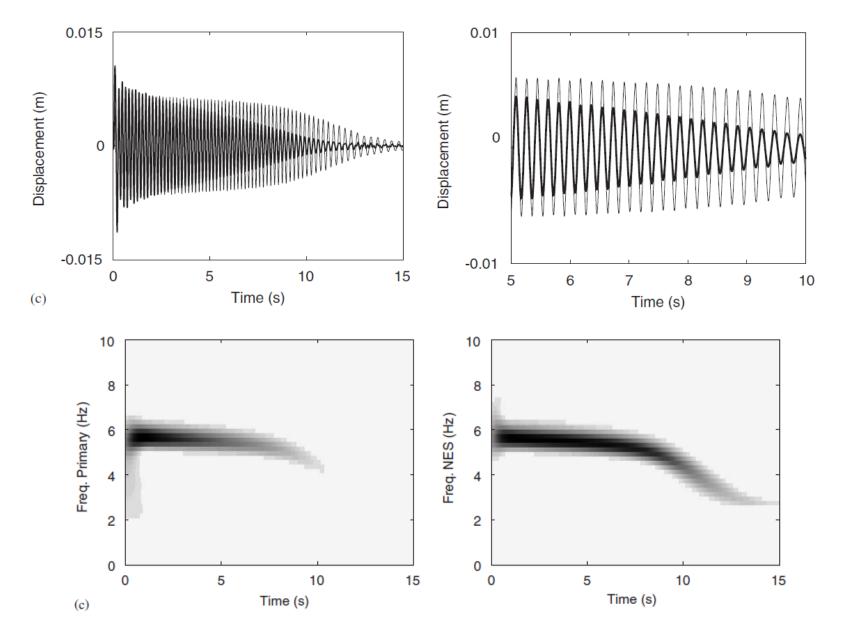
$$M\ddot{y} + \epsilon\lambda_1\dot{y} + \epsilon\lambda(\dot{y} - \dot{v}) + \epsilon(y - v) + ky = 0$$
$$m\ddot{v} + \epsilon\lambda_2\dot{v} + \epsilon\lambda(\dot{v} - \dot{y}) + \epsilon(v - y) + Cv^3 = 0$$



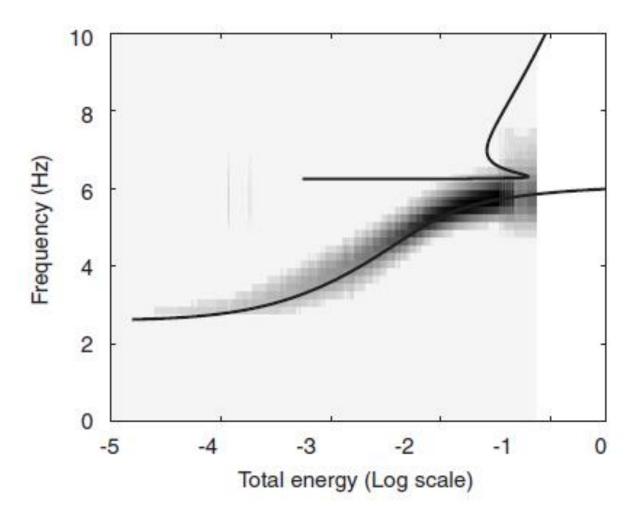
### What You See Is a Nonlinear Normal Mode



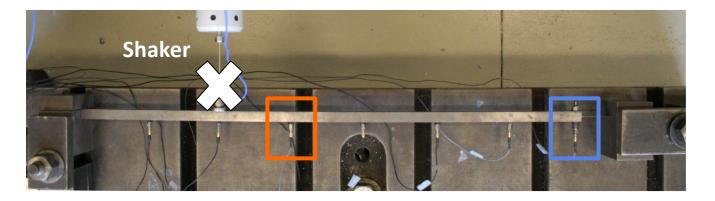
#### **Experimental Demonstration**



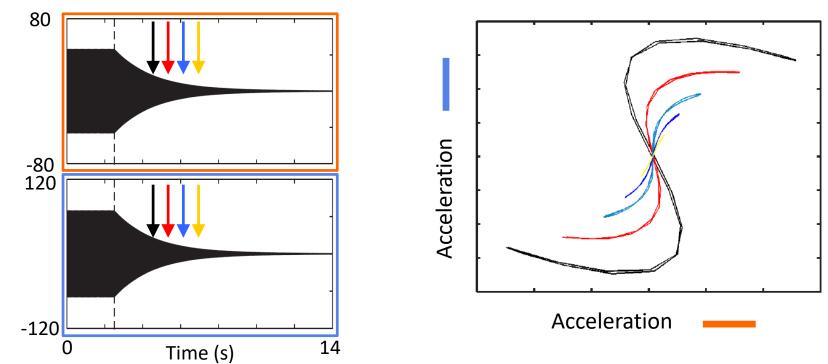
#### What You Have Just Seen



#### What You See Is a Nonlinear Normal Mode



Acceleration (m/s<sup>2</sup>)



What are nonlinear modes ?

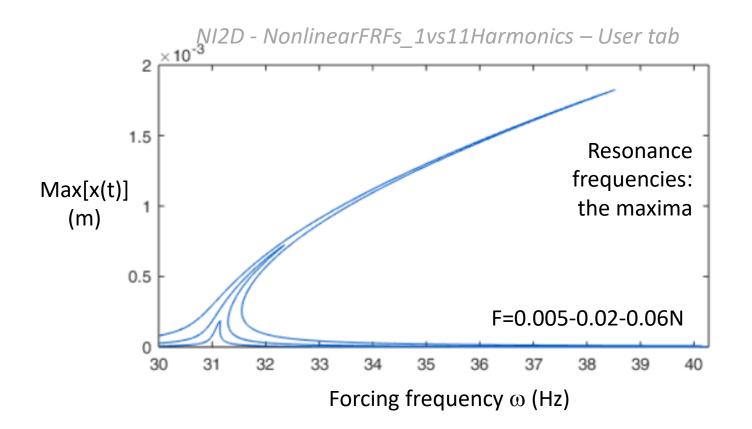
What are their fundamental properties ?

Link between modes and resonance frequencies

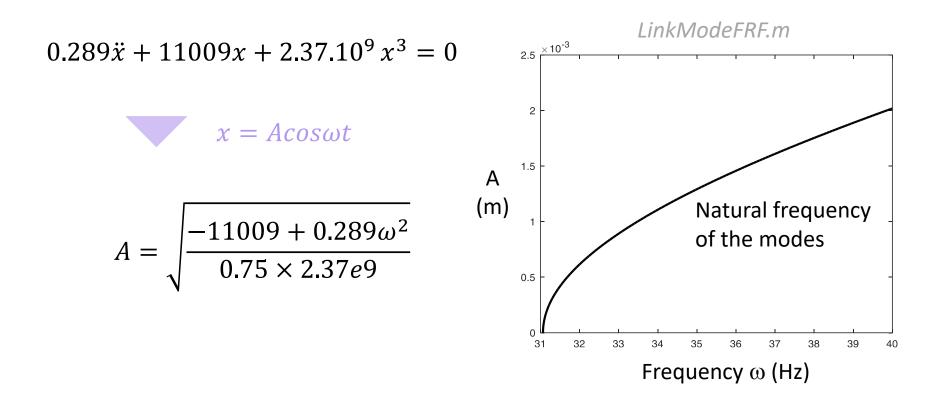
A tutorial

#### Forced/Damped Response of the Beam (L02)

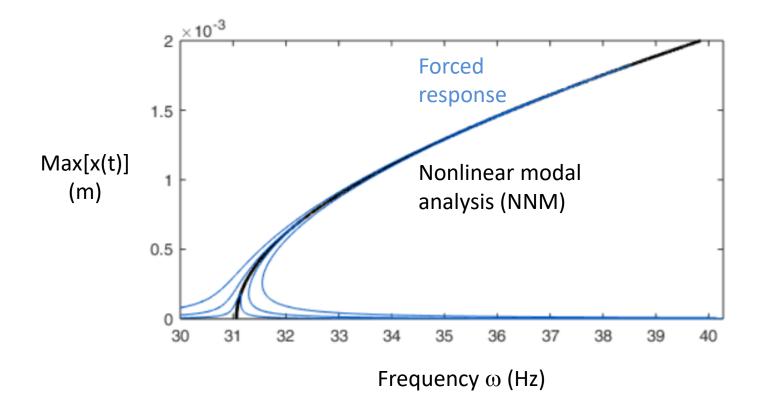
#### $0.289\ddot{x} + 0.1357\dot{x} + 11009x + 2.37.10^9 x^3 = Fsin\omega t$



#### Free/Undamped Response of the Beam



#### Link between Natural/Resonance Frequencies ?



NNM can predict the locus of resonance frequencies for various forcing amplitudes !

Clear physical meaning	LNMs	NNMs
Structural deformation at resonance	YES	YES
Synchronous vibration of the structure	YES	YES, BUT
Important mathematical properties		
Orthogonality	YES	NO
Modal superposition	YES	NO
Invariance	YES	YES