Satellite Engineering Overview & Conclusion

Ir. Julien Tallineau Tel: +32 472 72 32 43 Julien.tallineau@gmail.com

Presentation to ULg (09/12/20) Satellite Design Lecture

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A satellite is a product sold for a given price to a customer

Products can be classified using their application (Earth Observation, Communication, Navigation), using their mass (1kg, 50kg, 100kg), using their standard (1U, 6U, 12U)

What is the price of these satellites?





Worldview-4: Earth Observation (2,800 kg)

Earth Observation 6U Cubesat (12kg)

What is the price of these satellites?



AerospaceLab - Gen1 (To be launched 2023)

How do people design satellites? What are the steps?

- I. Customer Need (Scientist)
- 2. Creation of System Requirements
- 3. Phase 0 (CDF Study)
- 4. Phase A (Feasibility Study)
- 5. Phase B (Preliminary Design)
- 6. Phase C (Final Design)
- 7. Phase D (Manufacturing / Testing)
- 8. Phase E (Launch / Commissionning & Operations)
- 9. Phase F (De-orbiting)

- Satellite Engineering
 I. Customer Need (Scientist)
- 2. Creation of System Requirements
- 3. Phase 0 (CDF Study)
- 4. Phase A (Feasibility Study)





Satellite Engineering

- 5. Phase B (Preliminary Design)
 - Detailed System Analysis
 - Preliminary Subsystem Analysis
 - Trade-offs
- 6. Phase C (Final Design)
 - Detailed Subsystem Analysis
 - Procurement
 - Qualification Testing





Satellite Engineering

- 7. Phase D
 - Manufacturing
 - Acceptance Testing
 - Requirement Verification
 - Shipment to Launch site



- Satellite Engineering
- 8. Phase E
 - Launch
 - Commissionning
 - Operations



- 9. Phase F (De-orbiting/End of Life)
 - None in this case

Satellite come in all shapes & colours







Grace

STRATEGIC ISSUES & TRENDS FOR THE SATELLITE MARKETS

2021-2030 TRENDS FOR THE SATELLITE INDUSTRY

On average **1,704 Satellites to be launched** every year by 2030



Satellite demand concentrated by 5 broadband mega-constellations



Market value generated over 2021-2030





of market value still with GEO satellites

On average 13 Commercial GEO satellites to be ordered every year

by 2030



of market value from governments

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> 2 BELGIAN SATELLITES





2 ACHIEVEMENTS

• PROBA-I (2001)

- Earth Imaging
- Technology Demo
- PROBA-2 (2009)
- Sun Observation
- Technology Demo



- PROBA-V (2013)
- Global Vegetation Monitoring
- Operational Mission

2 ACHIEVEMENTS

• PROBA-I (2001)

- Earth Imaging
- Technology Demo

PROBA-2 (2009)

- Sun Observation
- Technology Demo
- PROBA-V (2013)
- Global Vegetation Monitoring
- Operational Mission



Mission

I. In orbit Demonstration, PROBA-2 aimed at technological innovation.

Altogether, 17 new technological developments and four scientific experiments are being flown on Proba-2.

Orbital Parameter			
LTAN	06:00 (AM)		
a (km)	7100		
e (deg)	0		
i (deg)	98		
w	0		

Mission

I. RAAN selected for 6:00 AM Local Time Ascending Node



- I. Launcher is Rockot
 - ▶ <u>Worst Case</u> separation rate of 8° per sec.
 - Inclination accuracy of 0.05°
 - Altitude accuracy of 12km
 - ► RAAN accuracy of 3.75° (≈15min LT)
- 2. Injected via the **Breeze upper stage**







- I. Ground segment visibility
 - REDU
 - KIROUNA



	Mean # contact	Mean duration of contact	Mean contact per day	Gap
Redu	5	8	35	11.5 hours
Kiruna	+/ - / = ?	+/ - / = ?	+/ - / = ?	+/ - / = ?

- I. Ground segment visibility
 - REDU
 - KIROUNA



	Mean # contact	Mean duration of contact	Mean contact per day	Gap
Redu	5	8	35	11.5 hours
Kiruna	9.5	8	77	10 hours

- I. Scenario
 - LEOP
 - Commissioning (three months)
 - Nominal Operations
- 2. Spacecraft Modes
 - Separation
 - Safe
 - Imaging
 - Stand-by





Satellite Design - Configuration

- I. Single H Structure
- 2. Sun Shield
 - Standard STR
 - Bepi-Colombo STR
- 3. High Unit Density



4. Deployable Solar Panel (x2)

Satellite Design - Mechanics

I. Spacecraft Mass ≈ 120 kg

2. CoG Choice

- Folded Configuration (LV requirement)
- Deployed Configuration (GNC requirement)

	Х	Y	Z		Х	Y	Z
COG (mm)	< 5	< 5	< 400	COG (mm)	< 20	< 5	< 400
MOI				MOI			
Х	<15	-I <xy< i<="" td=""><td>-I<xz< i<="" td=""><td>Х</td><td><15</td><td>- <xy< td="" <=""><td>-I<xz< i<="" td=""></xz<></td></xy<></td></xz<></td></xy<>	-I <xz< i<="" td=""><td>Х</td><td><15</td><td>- <xy< td="" <=""><td>-I<xz< i<="" td=""></xz<></td></xy<></td></xz<>	Х	<15	- <xy< td="" <=""><td>-I<xz< i<="" td=""></xz<></td></xy<>	-I <xz< i<="" td=""></xz<>
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Satellite Design - Power

I. Power budget is positive, independently of the mode

Observation (w/o & with TX)

Orbit 1: observation mode w/o TX

119.8

149.6

179.3

209.0

90.1

Safe mode with TX

Requirement

0.0

30.7

Battery DoD (Ah) < 20%

60.4





Satellite Design - Power

- I. Power budget while de-tumbling !
- 2. Trade-off between:
 - Performance (GNC)
 - Time (LEOP schedule)
 - Battery Discharge (Higher DoD)

Top: Incoming power (black), power consumption (red, and power to battery (green) [W]; Bottom: battery DoD [Ah]



Satellite Design - Avionics

- I. System is fully redundant
- 2. Data & Power centralized (ADPMS)
- 3. Interface Unit
 - AOCS Module
 - Deployment Module
 - Propulsion Module
 - Thermal Control Module



Satellite Design – AOCS

- I. Low power resistojet (Xenon)
 - ▶ I5W for heater (x2)
 - 50s lsp (min)
 - 20mN Thrust
 - Total $\Delta V = 2m/s$



$$\Delta u = V_{eq} \ln \left(\frac{mf}{me}\right) = V_{eq} \ln MR = lsp g_o \ln MR$$

Satellite Design – AOCS

- I. Sensors
 - 2 Star-tracker
 - > 2 GPS RX
 - 2 Magnetor-Meter







2. Actuators

- 4 Reaction Wheels
- 3 dual-coil magneto-Torquer





GPS RX





 \Rightarrow Position determination

Magnetometer (2)

Measure continuously the Earth Magnetic field and determine itselve where the North is.





Star-Tracker (3)

- Takes pictures of stars
- Compare it with its internat catalog.
- Compute the satellite orientation/position




2 PROBA - 2





- Magnetic Coil
- Align itself to Magnetic lines

\Rightarrow Orientation/Manoeuvre

2 PROBA - 2

Rection Wheel (4)

Accelerates or decelerates while momentum conservation implies the PROBA to rotate the other way.

⇒ Orientation/Manoeuvre





Mission

I. Providing **Daily Vegetation Global Monitoring** Capability to Scientific Community

	Key Performance data
Orbit	Quasi SSO (slightly drifting LTDN – injection 10:45 AM) i = 98.73 deg e = 0 Altitude = 820km
Mission Lifetime	2.5 year
Daily global coverage	Latitudes 35° to 75°N Latitudes 35° to 56°S
Coverage after two days	Latitudes between 75°N and 56°S

Mission

I. RAAN selected for 10:45 Local Time Descending Node.



Mission

- I. Launcher is VEGA
 - Semi-major axis accuracy of 15km
 - Inclination accuracy of 0,15 deg
 - Better than PSLV
 - Inclination accuracy of 0.2°
 - Altitude accuracy of 35km
- 2. Launch site: Kourou
- 3. Launch Date: 7th of May 2013



Mission

- I. Ground station selection
 - Svalbard / Kiruna / Fairbanks Payload data downlink
 - REDU for mission control

	Svalbard	Redu	Kiruna	Alaska
Location	Norway	Belgium	Sweden	Fairbanks
Controlled by	KSAT	ESA	SSC	USN
Co-ordinates	78.13 ⁰N, 15.23ºE	50.01°N, 5.14°E	67.85°N, 20.96°E	64.9°N, 147.9°W
Antenna diameter [m]	11/13	2.4	15/13	10
Bands available	S/X	S	S/X	S/X
Min Elevation [Deg]	5	5	5	5
EIRP [db]	64	72.5	71/69	24/37
G/T, sensitivity [db]	35.4	29 (S)	21.4/35.6	22/32
Altitude [m]	455	386.6	402	149

Source: ESA ESTRACK manual

Mission

- I. Ground station selection
 - Fairbanks & Kiruna overlap! No steerable antenna on board
 - Necessity to interrupt connection



Satellite Design - Configuration

- I. X-band antenna toward Nadir
- 2. Solar Array on Velocity, Zenith & Anti Velocity
- 3. Star Tracker looking as much as possible towards deep space



Satellite Design - Structure

- I. Single H structure
- 2. Stiffening beams



- 3. Honeycomb panels
 - Aluminium core
 - Aluminium edge
 - Alumiunium facesheet (Primary structure)
 - CFRP facesheet (Secondary structure)



Satellite Design - Mechanics

I. Spacecraft Mass = 148 kg with given margin philosophy

	Mass (w/o margin)	Margin	Mass w/ margin	Note
Unit I	5kg	5%	5.25kg	No modification
Unit 2	2kg	10%	2.2 kg	Modification
Unit 3	3kg	20%	3.6 kg	New development
TOTAL	10 kg		11.05 kg	w/o Sys Margin
	System Margin	20%	13,26kg	w/ Sys Margin

2. Balance Mass of for CoG Location Requirement

Launcher	Lateral Tolerance [mm]	Longitudinal Tolerance [mm]
VEGA	10	< 500

Satellite Design - Power

- I. Power budget approach could be:
 - Rely on Solar Array (SA) in Sun and on Battery in Eclipse
 - Rely on both Battery and SA when available.

What are the advantages & disadvantages of these approaches?



Satellite Design - Power

I. Power budget approach could be:

Rely on Solar Array (SA) in Sun and on Battery in Eclipse

Rely on both Battery and SA when available.

	IMAGING	X-BAND	STD-BY
PDHU	20₩	20₩	20₩
COM	5₩	40₩	5W
PAYLOAD	32\V	5₩	5W
TOTAL	85 W	120 W	40₩
Sys Marg	5%	5%	5%
TOTAL	90W	125W	45W
		Τ.	

Typical power budget

- Power Generation
 & Storage
 - Solar Array
 - Battery
- 2. Power Conditioning Distribution Unit (not displayed)



- 3. Connections
 - Safe & Arm
 - Umbilical Connection

I. Main components

- Cells Series (TBD)
- String Parallel (TBD)
- Section (TBD strings)



2. Secondary components (not displayed)

- Shunt Selection
- Dump Resistor



- 2. Secondary components (not displayed)
 - Shunt Selection
 - Dump Resistor



Isc = current in short circuit Uoc = Voltage in open circuit Mpp = max power point

- Solar Array Design (3G28%)
- I. Evaluate the degradation?
 - Coverglass thickness

Coverglass thickness (µm)	Pr	nax [[#/cm²]	Voc	[#/cm ²]	Isc [#/cm ²]	
0,0		5,11E+17 5,99E+17		7,12E+17			
25,4		7,64E	E+14	8,9	3E+14	8,43E+14	
76,2	1,52E+14		1,76E+14		1,35E+14		
152,4	7,81E+13		8,9	9E+13	6,48E+13		
304,8		4, 1 <mark>6</mark> 8	E+13	4,7	5E+13	3,27E+13	
508,0		2,53	E+13	2,8	8E+13	1,94E+13	
762,0		1,64	+13	1,8	6E+13	1,16E+13	
1524,0),20E	+12	9,3	7E+12	5,43E+12	

3G-28% cell: Electrical Parameters drift pradi tic

EP	BoL	2,00E+13	7,00E	13	2,50E+14	5,00E+14	1,00E+15	3,00E+15
Voc	2650	0,98	C	97	0,95	0,94	0,92	0,9
lsc	498	0,99	C),59	0,99	0,98	0,96	0,87
Vmp	2365	0,99	(),9	0,94	0,93	0,92	0,9
Imp	480	0,99	C),99	0,98	0,97	0,95	0,84
Pmp	1135	0,98	C),97	0,92	0,91	0,87	0,76

 Degradation of Electrical Parameters



3G-28% cell: Temperature Coefficients drifts in dation

TC	BoL	2,00E+13	7,00E+13	5,00E+14	1,00E+15	3,00E+15
Voc (mV/K)	-5,96	-6,01	-6,11	-6,15	-6,25	-6,46
lsc (mA/K)	0,348	0,298	0,298	0,340	0,370	0,340
Vmp (mV/K)	-6,01	-6,42	-6,45	-6,26	-6,35	-6,59
Imp (mA/K)	0,316	0,248	0,219	0,220	0,250	0,220
Emp (mW/K)	-2,54	-2,60	-2,69	-2,66	-2,59	-2,42

Degradation of Temp.
 Coefficient

What happens to the Pmax at EoL?



Consider both radiation and thermal effect

Parameters

Example using 3G28%

I. Evaluate the degradation?

Degradation of Electrical

Coverglass thickness

Coverglass thickness (µm)	Pmax [#/cm ²]	Voc [#/cm ²]	Isc [#/cm ²]
0,0	5,11E+17	5,99E+17	7,12E+17
25,4	7,64E+14	8,93E+14	8,43E+14
76,2	1,52E+14	1,76E+14	1,35E+14
152,4	7,81E+13	8,99E+13	6,48E+13
304,8	4,16E+13	4,75E+13	3,27E+13
508,0	2,53 E+13	2,88E+13	1,94E+13
762,0	1,641 +13	1,86E+13	1,16E+13
1524,0	2,20E +12	9,37E+12	5,43E+12

3G-28% cell: Electrical Parameters drifte pradictio

EP	BoL	2,00E+13	7,00E	13	2,50E+14	5,00E+14	1,00E+15	3,00E+15
Voc	2650	0,98	C	97	0,95	0,94	0,92	0,9
lac	498	0,99	C	, <u>t</u> 9	0,99	0,98	0,96	0,87
Vmp	2365	0,99	C	,9	0,94	0,93	0,92	0,9
Imp	480	0,99	C	,99	0,98	0,97	0,95	0,84
Emp	1135	0,98	C	,97	0,92	0,91	0,87	0,76

3G-28% cell: Temperature Coefficients drifts in radiation

TC	BoL	2,00E+13	7,00E+13	5,00E+14	1,00E+15	3,00E+15
Voc (mV/K)	-5,96		-6,11	-6,15	-6,25	-6,46
lsc (mA/K)	0,348	Ļ	0,298	0,340	0,370	0,340
Vmp (mV/K)	-6,01	-6,42	-6,45	-6,26	-6,35	-6,59
Imp (<u>mA</u> /K)	0,316	0,248	0,219	0,220	0,250	0,220
Pmp (mW/K)	-2,54	-2,60	- <mark>2,6</mark> 9	-2,66	-2,59	-2,42

Degradation of Temp.
 Coefficient



2. Evaluate the number of cells ?

- Consider worst case (EoL + Hot temperature $\approx 100^{\circ}$ C)
- Max battery voltage to be provided (e.g. 28V)

	Voltage	
Harness voltage drop (incl. connectors)	<	V
Solar Array connectors & protections (e.g. diodes)	<	V
Maximum Battery Voltage	28	V
Minimum solar cell strings voltage required	28+1+1=30	V
Additional voltage margin	I	V
Required solar string voltage	31	V
EoL cell voltage @ 100°C	1,8	V
Required amount of cell to cells in one string to achieve voltage	18	Cells

- 3. Evaluate the number of strings ?
 - Max current allowed by PDHU (e.g. 12A) @BOL
 - Compute current available at EOL, knowing that di/dT < 0 and accounting for Minimum Solar Cste (di/dC > 0)

	Current	
Assuming best case = direct illumination, BOL, hot case	-	-
BOL string current	0.5	A
BOL maximum amount of string	24	strings
Assuming worst case = 10% shading, low solar constant, cold case	-	
EOL degradation factor	90%	
EOL string current	0.45	A
Shading degradation (10% of 24 strings shaded)	3	strings
Total current available at EOL (from $24 - 3 = 21$ strings)	9,45	A

Satellite Design - Power

- I. Then put it all over an realistic scenario and iterate
- 2. At the end of the day, only 9+8+8 strings* were sufficient.



Note: 9+8+8 means 9 strings on one panel 8 string on two other panels

60

I. Main components

- Cells Series (TBD)
- String Parallel (TBD)
- 2. Secondary components
 - Internat heaters
 - Thermistors



Main components
 Cells Series (TBD)
 String Parallel (TBD)

How can we calculate this?

- 2. Secondary components
 - Internat heaters
 - Thermistors



I. Evaluate the number of cells ?

- Check Nominal non regulated bus voltage requirement (28V)
- Find Cells characteristics (e.g. 4V End of Charge EoL)
- Combine 7 cells in series to create the voltage



2. Battery shall be used for

- Standby in eclipse
- Any mode during Sun Light
- Detumbling

3. Evaluate the number of strings ?

- Capacity_{used} = Power * Time
- Capacity_{required} = Capacity_{Used}/DoD_{Allowed}
- Capacity of I string = Nb_{Cells}*Capacity_{Cell}
- One String Failure Tolerance

5 (+1) Strings



Example	Used Capacity (Wh)
Standby in Eclipse	45W * 0,75h = 33,75Wh

Example	DoD choice	Required Capacity (Wh)
Eclipse	20%	169

Parameter	Value
Nb _{Cells}	7
Capacity _{Cell}	5,4 Wh
Capacity I string	37,8 Wh

Satellite Design – RF COM

- I. Downlink (S-Band) 2235 MHz
 - Data rate = I42kbps (BPSK modulation)
 - Symbol rate = 329 ksps (Convolutional-Reed Solomon Coding)

Two things to look at:

- Flux margin (avoid too much power received on grd)
- Telemetry Recovery margin (avoid too little power to read the telemetry) (Eb/N0)
- Good practice = 3 dB



Satellite Design – RF COM

- I. How to make quick check for Flux Density?
 - +Power @ Transmitter (dBW)
 - Circuit Loss (3dB)
 - +S/C Gain of Antenna (dBi)
 - 10*LOG(4*π*(slant_km*1000)²)
 - = Power Flux @ G/S (dBW/m²)
 - -10*LOG(bit_rate_kbps)+6+30

= Power Flux Density @ G/S (dBW/m²/4kHz) shall be < Required

FIRP

Satellite Design – RF COM

- 1. How to make quick check for TM Recovery margin?
 - +Power @ Transmitter (dBW)
 - Circuit Loss (3dB)
 - +S/C Gain of Antenna (dBi)
 - Path Loss (dB) Atmosphere & Polarization mismatch (IdB)
 - ▶ + G/T of the Antenna (dB/K)
 - Boltzmann constant (dBW/HzK)
 - = C/N0 (carrier to noise ratio) (dBHz)
 - TM Demodulation Loss (dB) depends on complexity
 - TM BitRate (dBHz)
 - Eb/N0 (dB) shall be > Required

Satellite Design – RF COM

- I. Downlink (S-Band) 2235 MHz
 - Data rate = 142kbps (BPSK modulation)
 - Symbol rate = 329 ksps (Convolutional-Reed Solomon Coding)
- 2. Uplink (S-Band) 2058 MHz
 - Data rate = 64kbps
 - Carrier Recovery margin of 20dB
 - Telecommand Recovery margin of 6dB



Satellite Design – Memory

I. Memory

- Mass Memory size = 90Gbit
- Required < 55 Gbit</p>
- Total Generated < 230 Gbit</p>



2. Ground contact

- 20 contact per day 8 skipped (assumption)
- Max time delay = 3,2 hours



Satellite Design – AOCS

- I. Guidance
 - = determination of the desired path of travel from the satellite's current location to a designated target
- 2. Navigation
 - = determination of the satellite's location, velocity and attitude

3. Control

= manipulation of the forces needed to track guidance commands while maintaining satellite stability



• What are the typical sources of error?



How much deviation does it give on ground if the satellite flies at 800 km?



(give it in 2-sigma & 3-sigma confidence)

Launched on the 07/05/2013 from Kourou




• 4 CASE STUDY







Mission

 ESA asks you to put two spacecrafts in High Elliptical Orbit (HEO) with 20 hours period so that one can occult the Sun while the other one collects picture of its Corona (scientific purpose)

Parameter	Value
Orbit type	HEO
Perigee altitude	600km
Apogee altitude	60,000km
Inclination	59°
Eccentricity	0.8

What are the advantages and disadvantages of such an orbit?



What would you put in your spacecraft ?

Subsystem	Design
Structure	Aluminum (density = 2700 kg/m³) CFRP (density = 1800 kg/m³) Invar (density = 8000 kg/m³)
Thermal	Passive OR Active ?
Mechanism	Body Mounted OR Deployable SA?
Power	Large OR Small SA ? Large OR Small Battery?
GNC	Sensor? + Why ? Actuator? + Why?
RF	High/Low Gain COM Antenna?

How would you Launch the two spacecrafts so that they reach the same orbit? (Two Launches? One Launch?)(Together? Separated?)

4 CONCLUSION

Summarizin G



4 CONCLUSION

I. Follows the Project Life Cycle

- Starts with Mission Concept
- Prepares System Requirements
- System Designs based on Technical & Programmatic Trade-Offs
- Prepare sub-system & unit requirement + analysis
- Link all levels together (= unit requirement verifying sub-system requirement, themselves verifying system requirements)
- Manufacture the S/C
- Verify Requirements (Review of Design / Analysis / Test)
- Launch it !
- 2. Iterative Multi-disciplinary approach + Massive Communication